



Introduction to Machine Learning

13. Learning Theory

Geoff Gordon and Alex Smola
Carnegie Mellon University

<http://alex.smola.org/teaching/cmu2013-10-701x-10-701>

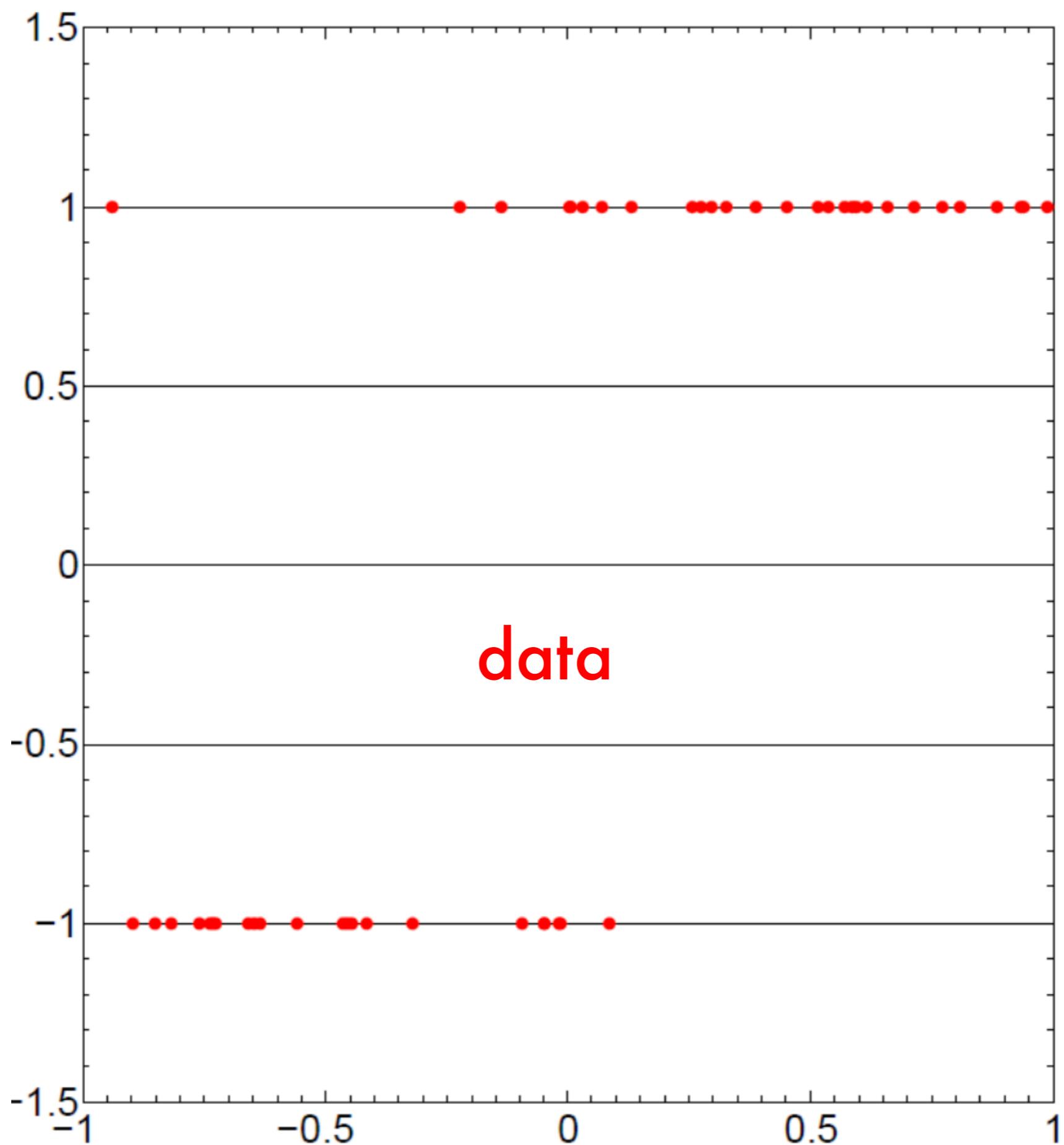
The Problem

- **Training**
 - **Data** $\{(x_1, y_1), \dots, (x_m, y_m)\}$ drawn iid from $p(x, y)$
 - **Loss function** $l(x, y, f(x))$
 - **Function class** $\mathcal{F} = \{f : \Omega[f] \leq c\}$
 - **Empirical risk minimization problem**

$$\underset{f \in \mathcal{F}}{\text{minimize}} \frac{1}{m} \sum_{i=1}^m l(x_i, y_i, f(x_i))$$

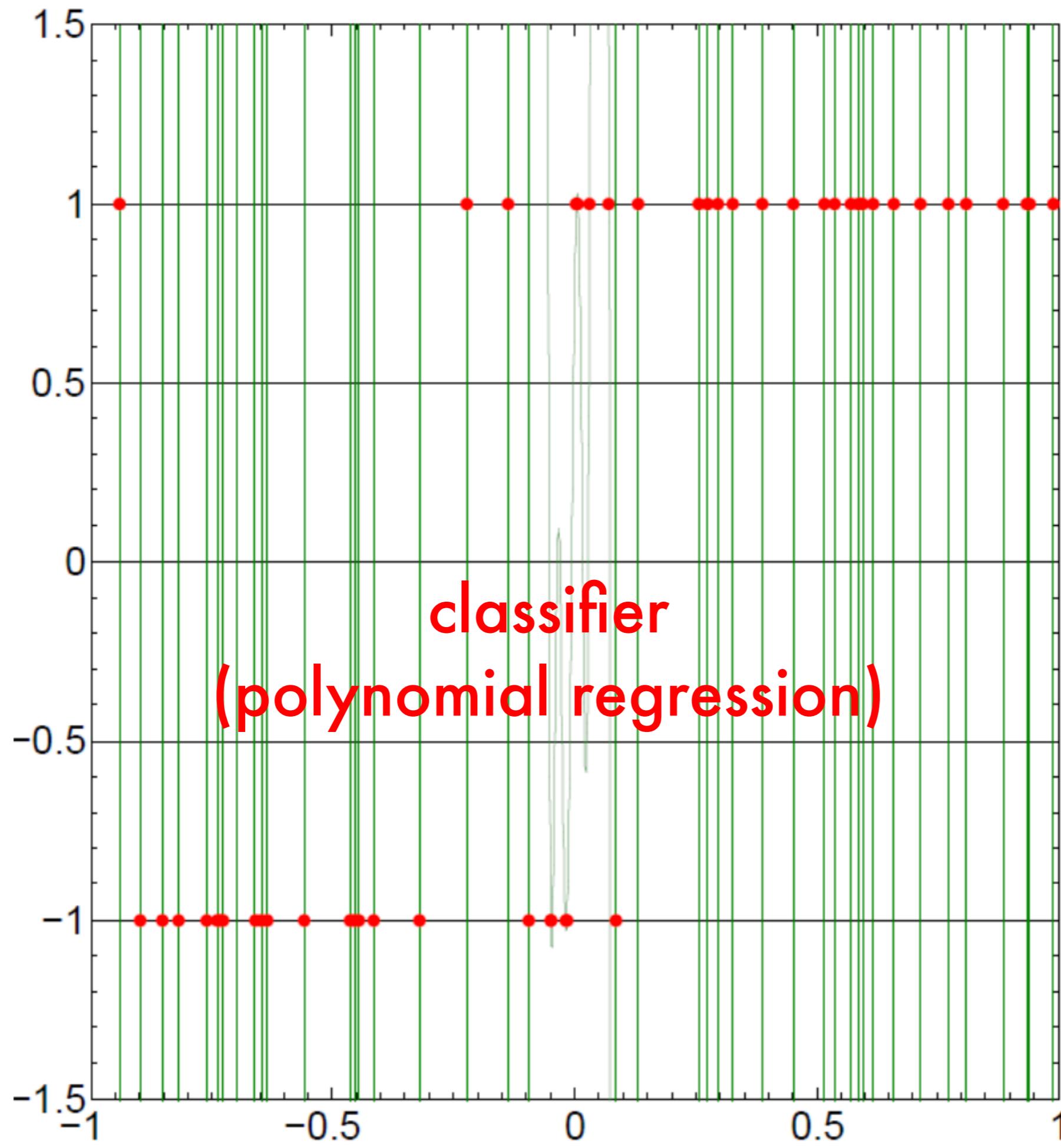
- **Testing**

$$\underset{(x,y) \sim p(x,y)}{\mathbf{E}} [l(x, y, f(x))]$$

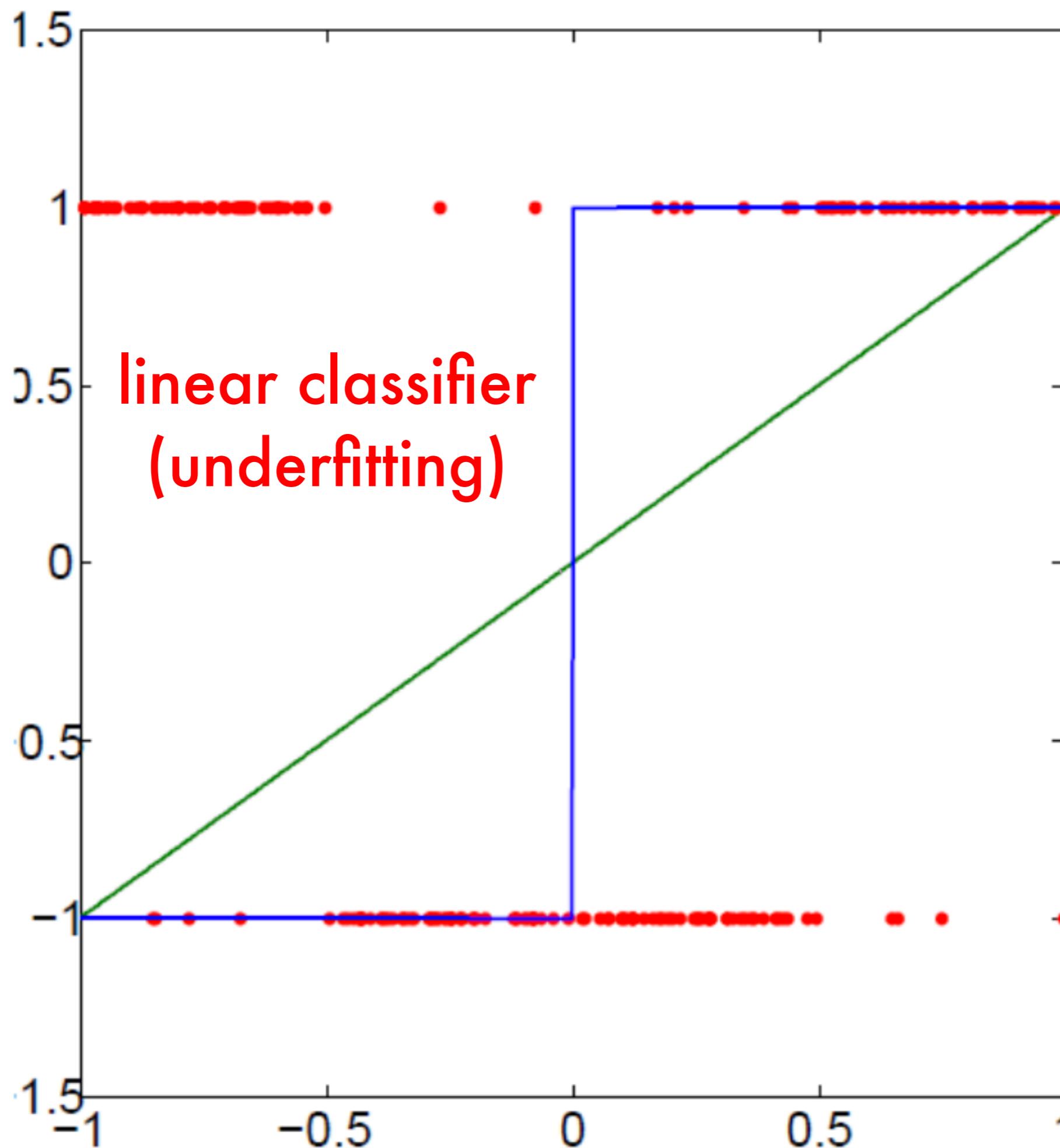


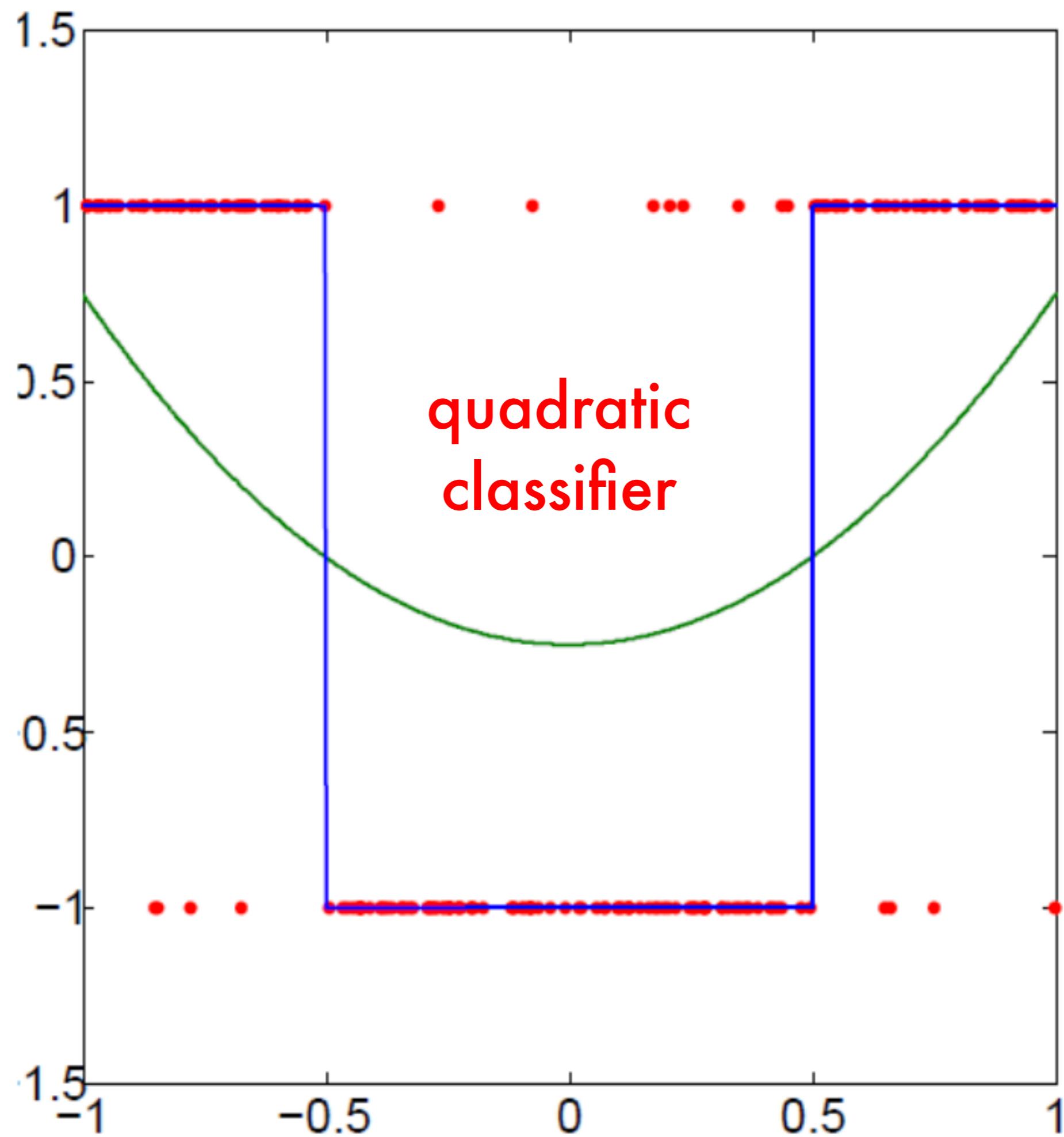
Picture from David Pal

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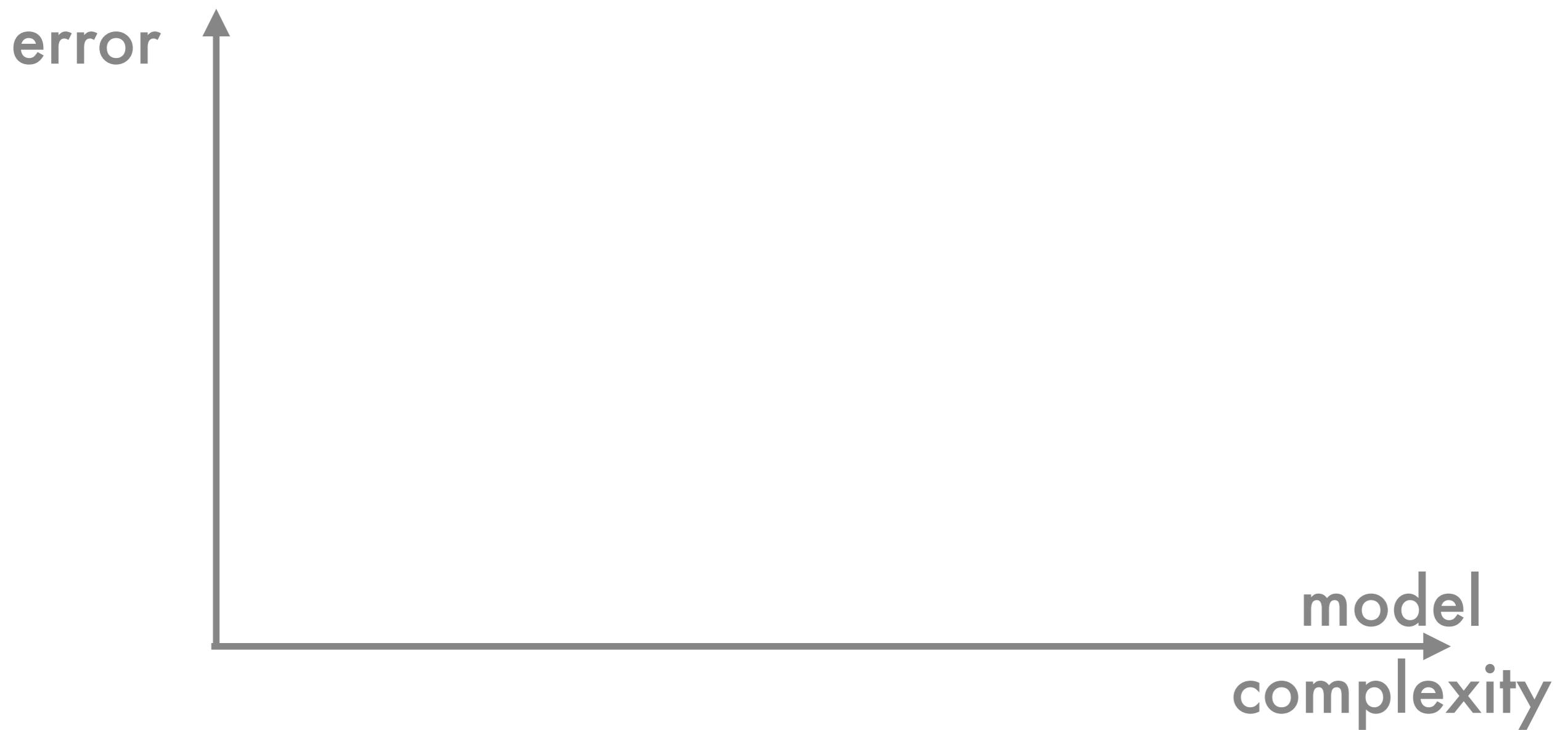


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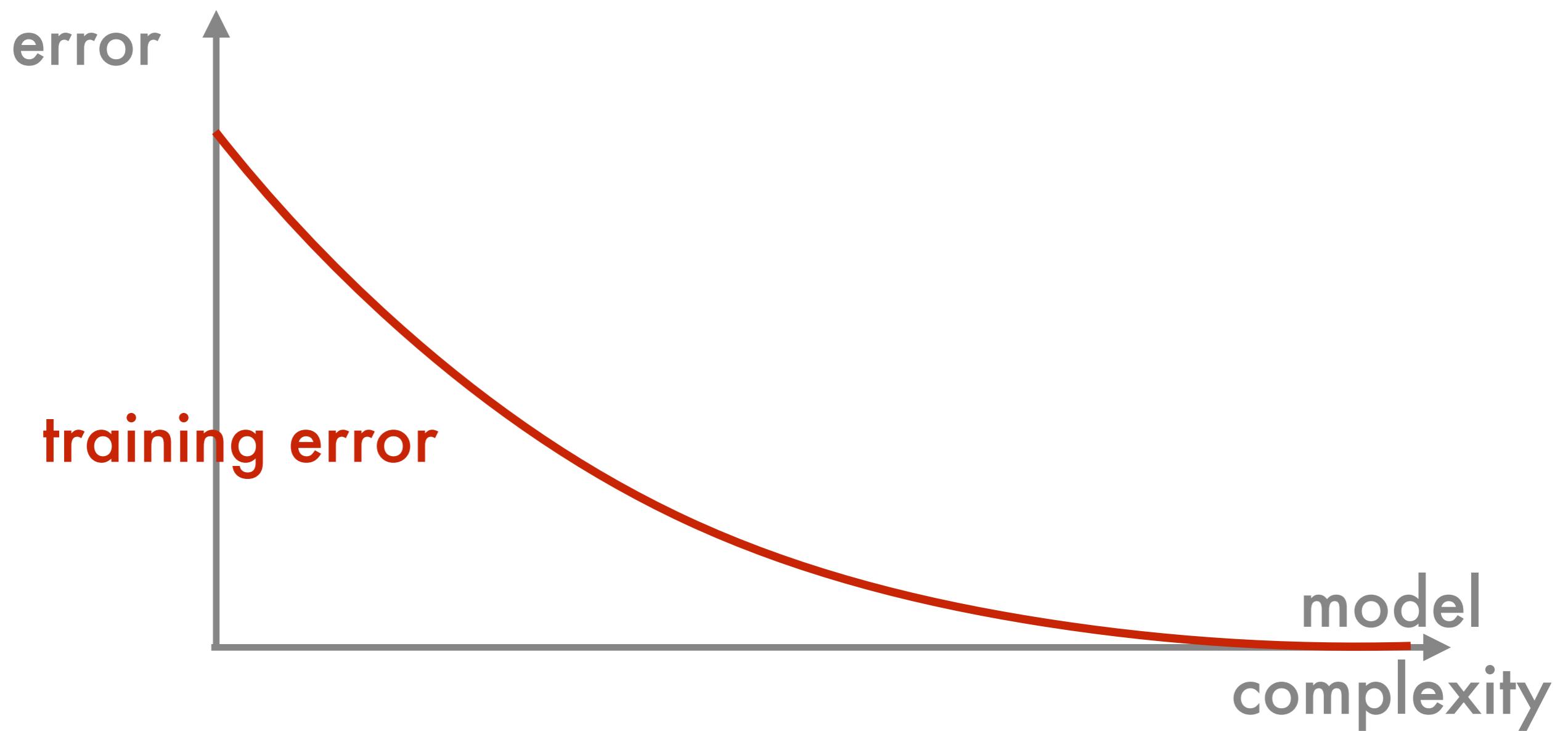




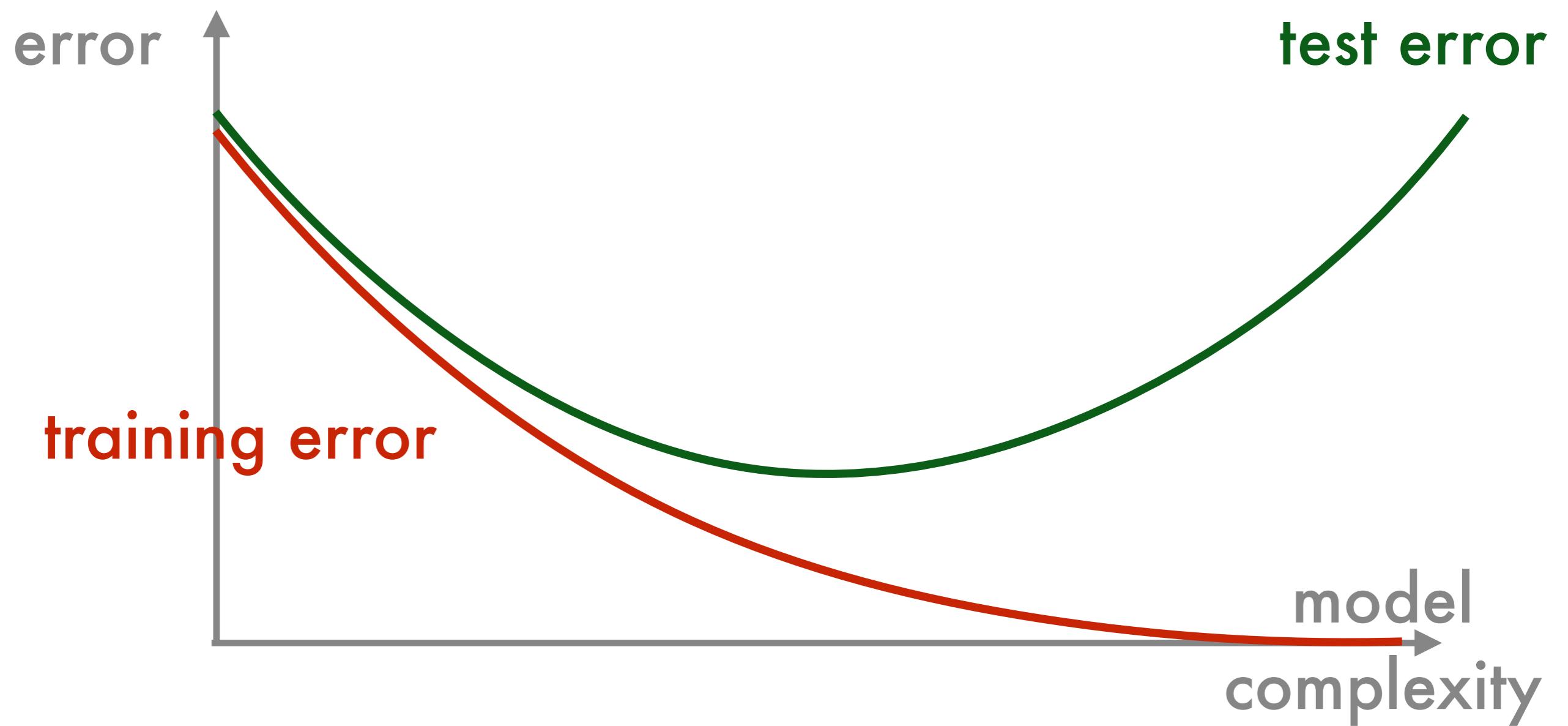
Typical behavior



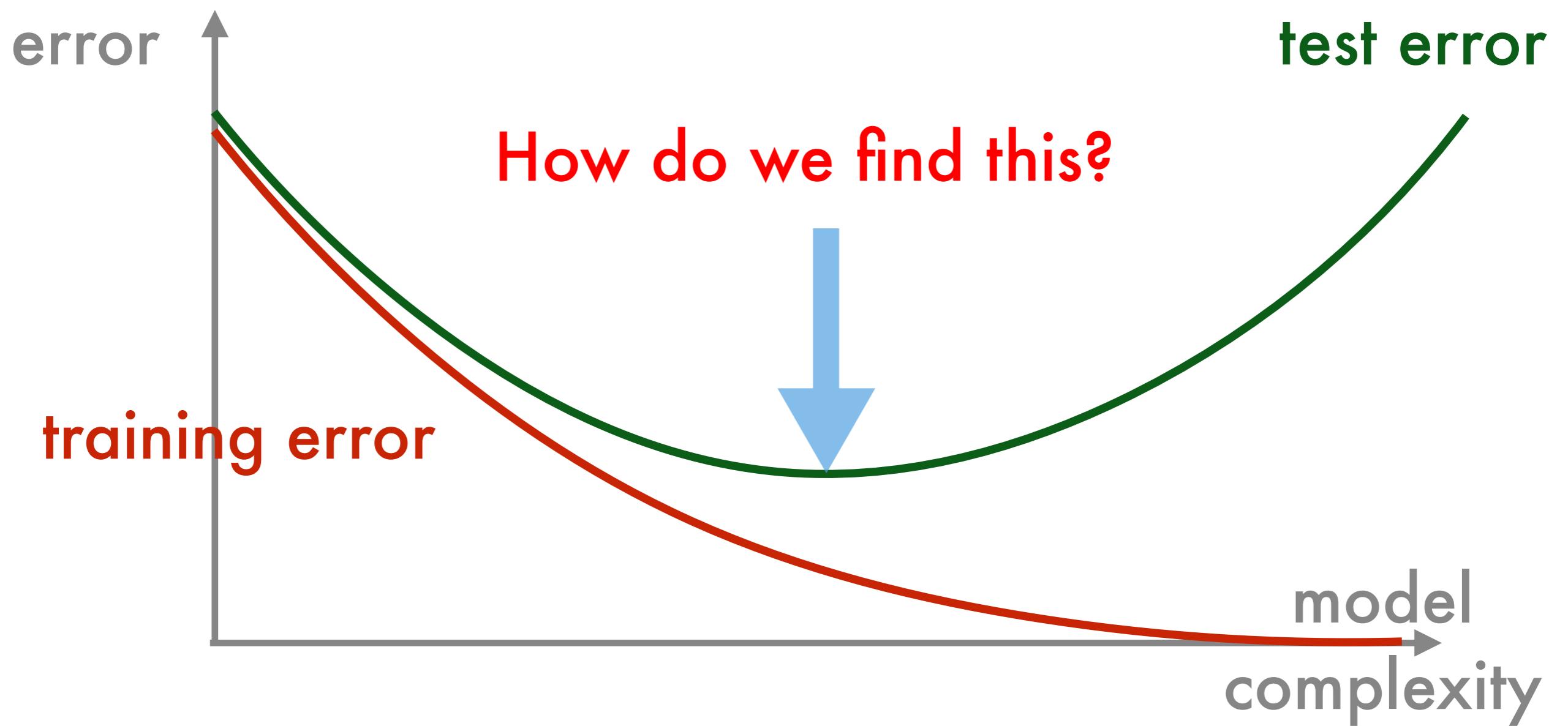
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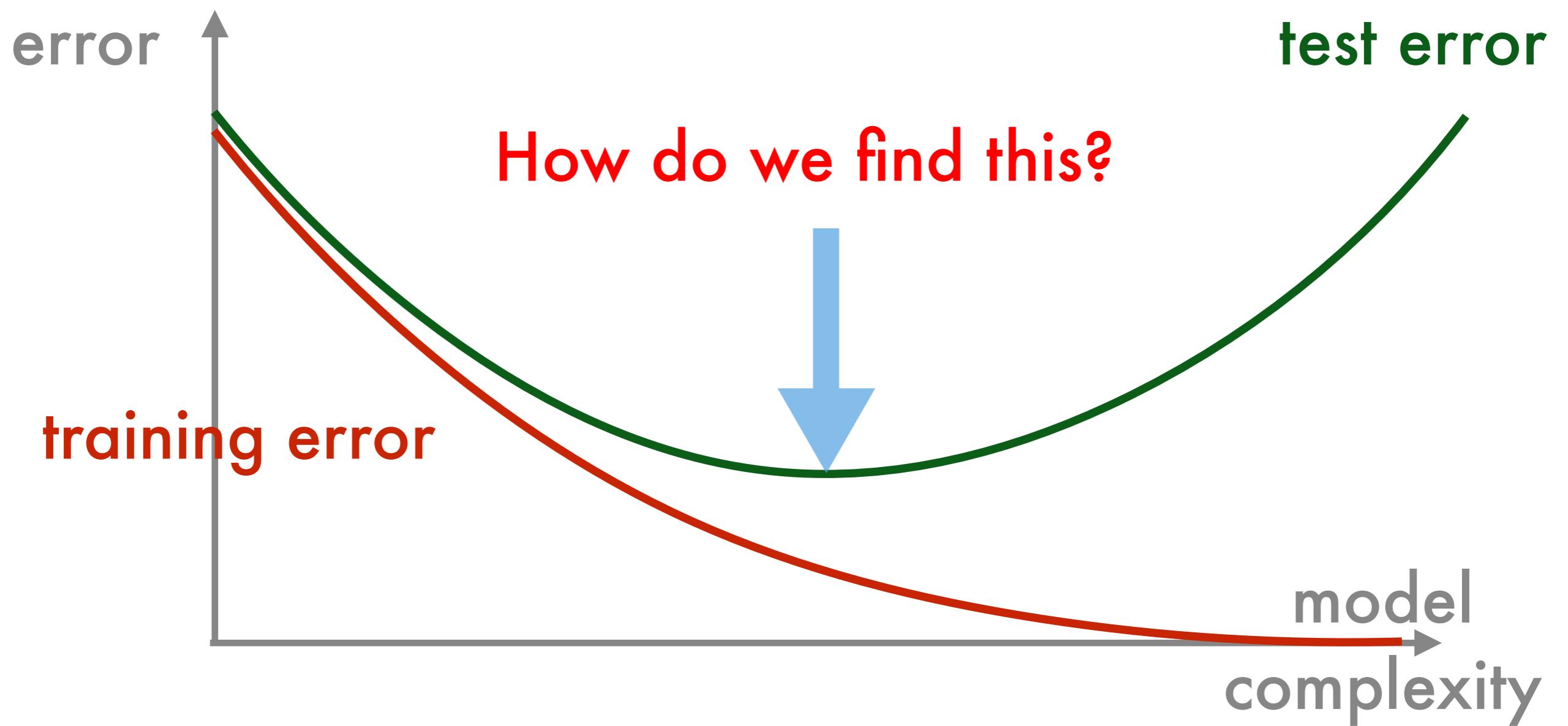
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A broken reasoning

- Hoeffding bound for bounded random variable

$$\Pr(|\hat{\mu}_m - \mu| > \epsilon) \leq 2 \exp\left(-\frac{2m\epsilon^2}{c^2}\right).$$

- Function f^* that minimizes empirical risk
- Bounded risk by L
- Apply bound to get with high probability

$$\epsilon \leq L \sqrt{(\log 2/\delta)/2m}$$

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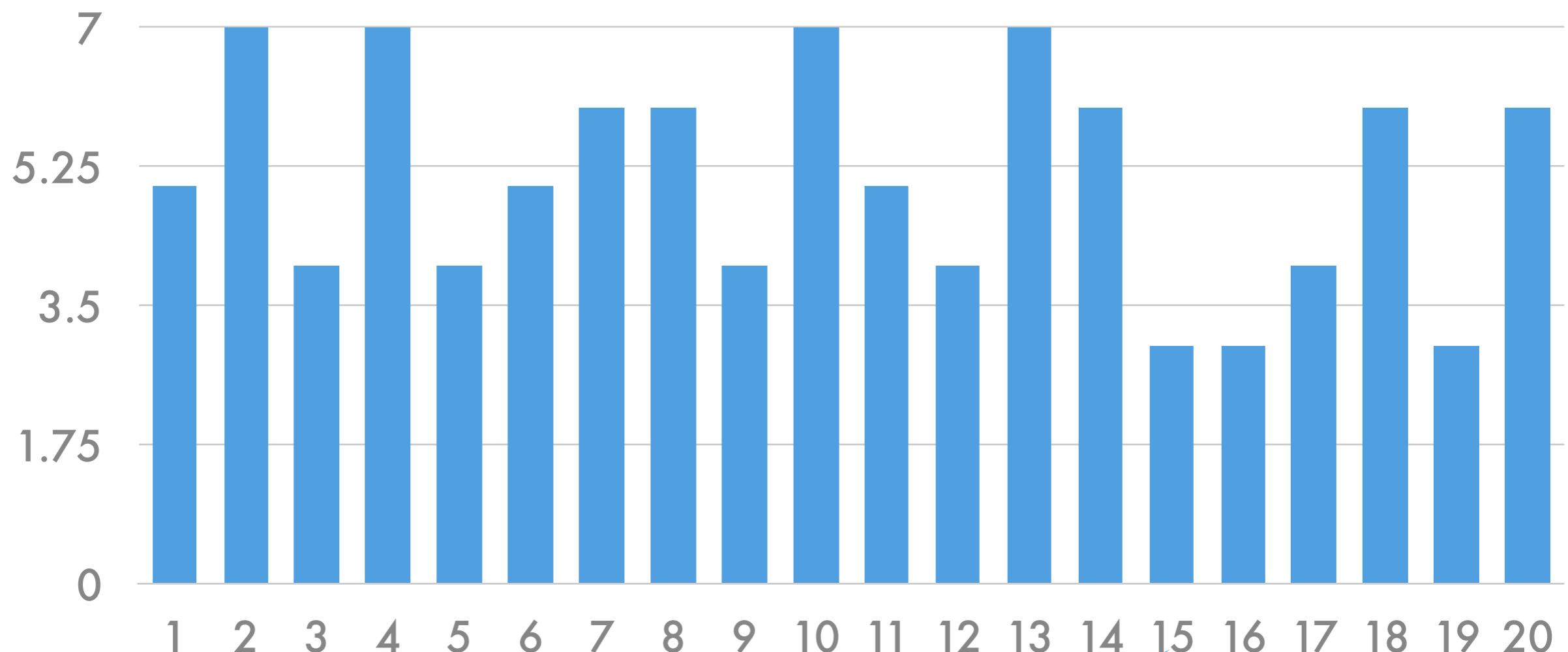
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- Why does our bound diverge in reality?

Multiple testing

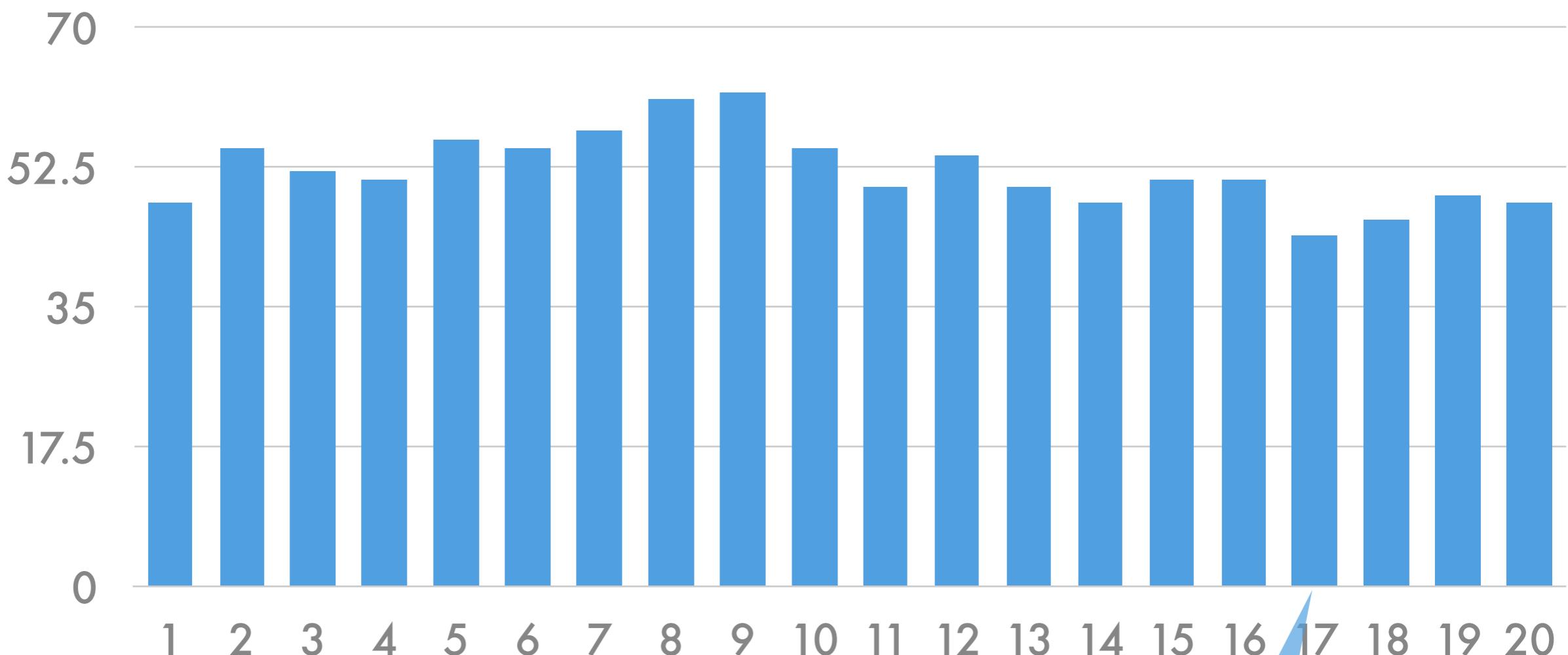
- Tossing an unbiased coin 10 times



best 'strategy'

Multiple testing

- Tossing an unbiased coin 100 times



best 'strategy'

Multiple testing

- We invoke the bound each time we test
- Picking the best out of N gives us N opportunities to get it wrong!
- Union bound

$$\Pr \{|R_{\text{emp}}[f] - R[f]| > \epsilon\} \leq \sum_{f' \in \mathcal{F}} \Pr \{|R_{\text{emp}}[f'] - R[f']| > \epsilon\}$$

- Testing over all functions in function class
 - Split error probability up among all functions
 - Take supremum over all terms

Multiple testing

- Our first generalization bound

$$\epsilon \leq L \sqrt{\frac{\log |\mathcal{F}| + \log 2/\delta}{2m}}$$

- Putting it all together

$$R[f^*] \leq \inf_{f \in \mathcal{F}} R_{\text{emp}}[f] + L \sqrt{\frac{\log |\mathcal{F}| + \log 2/\delta}{2m}}$$

Multiple testing

- Our first generalization bound

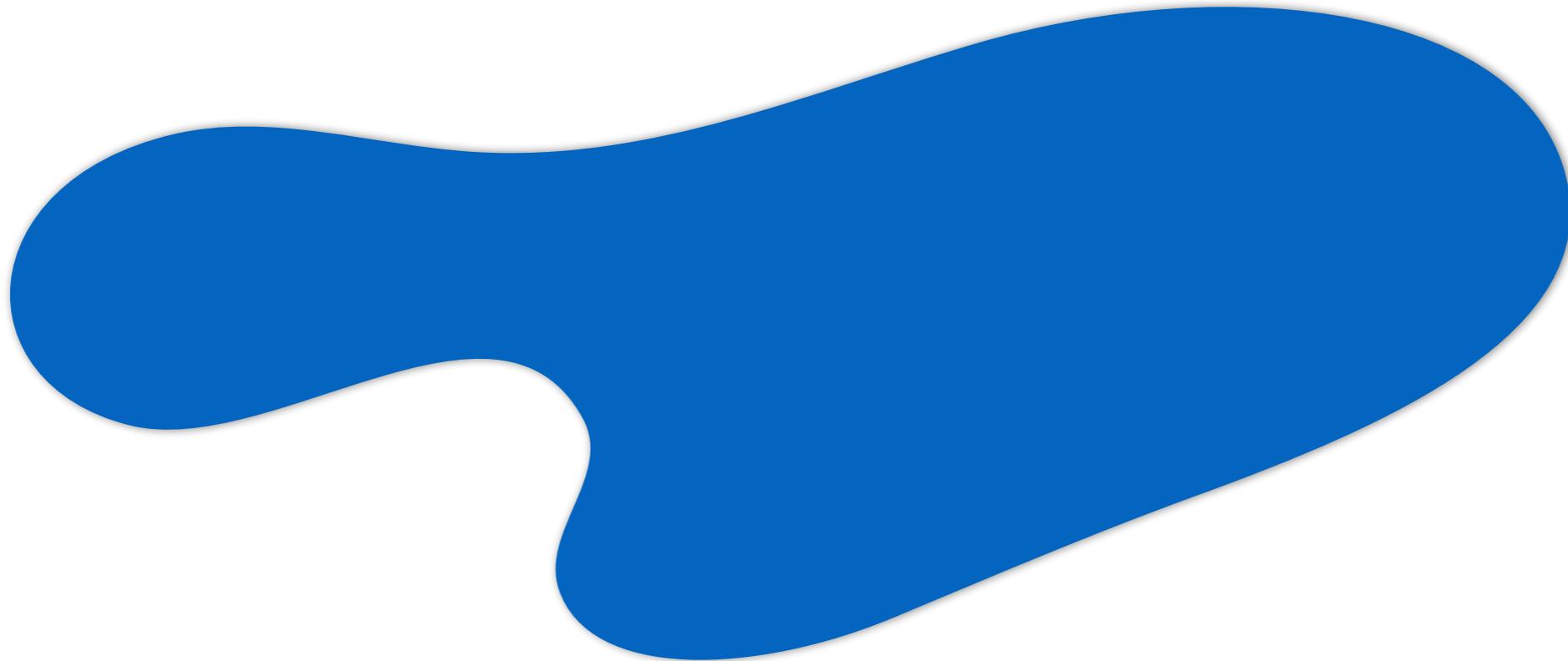
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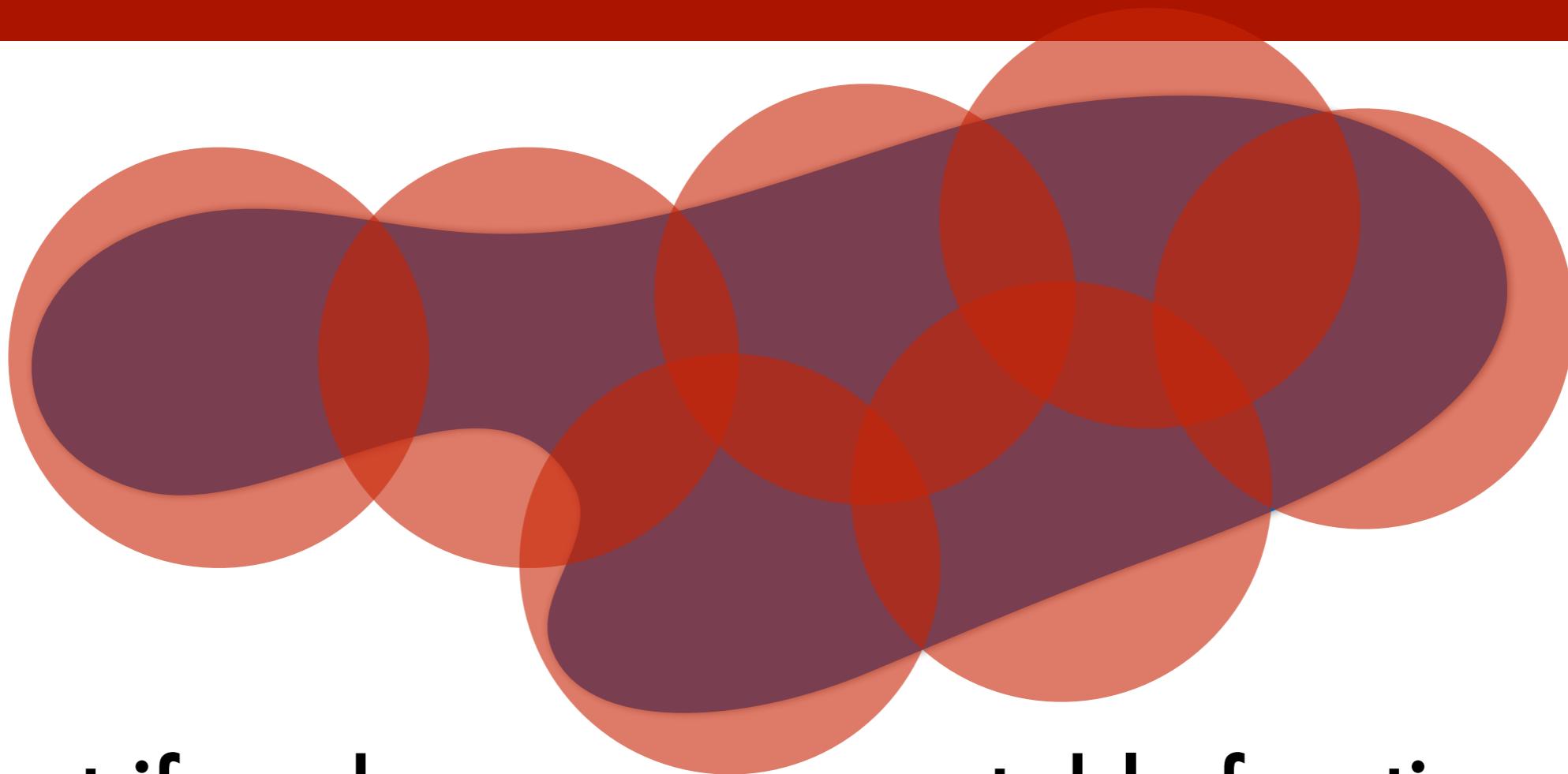
- What if function class is not discrete?
- What if we have binary loss

Covering Numbers



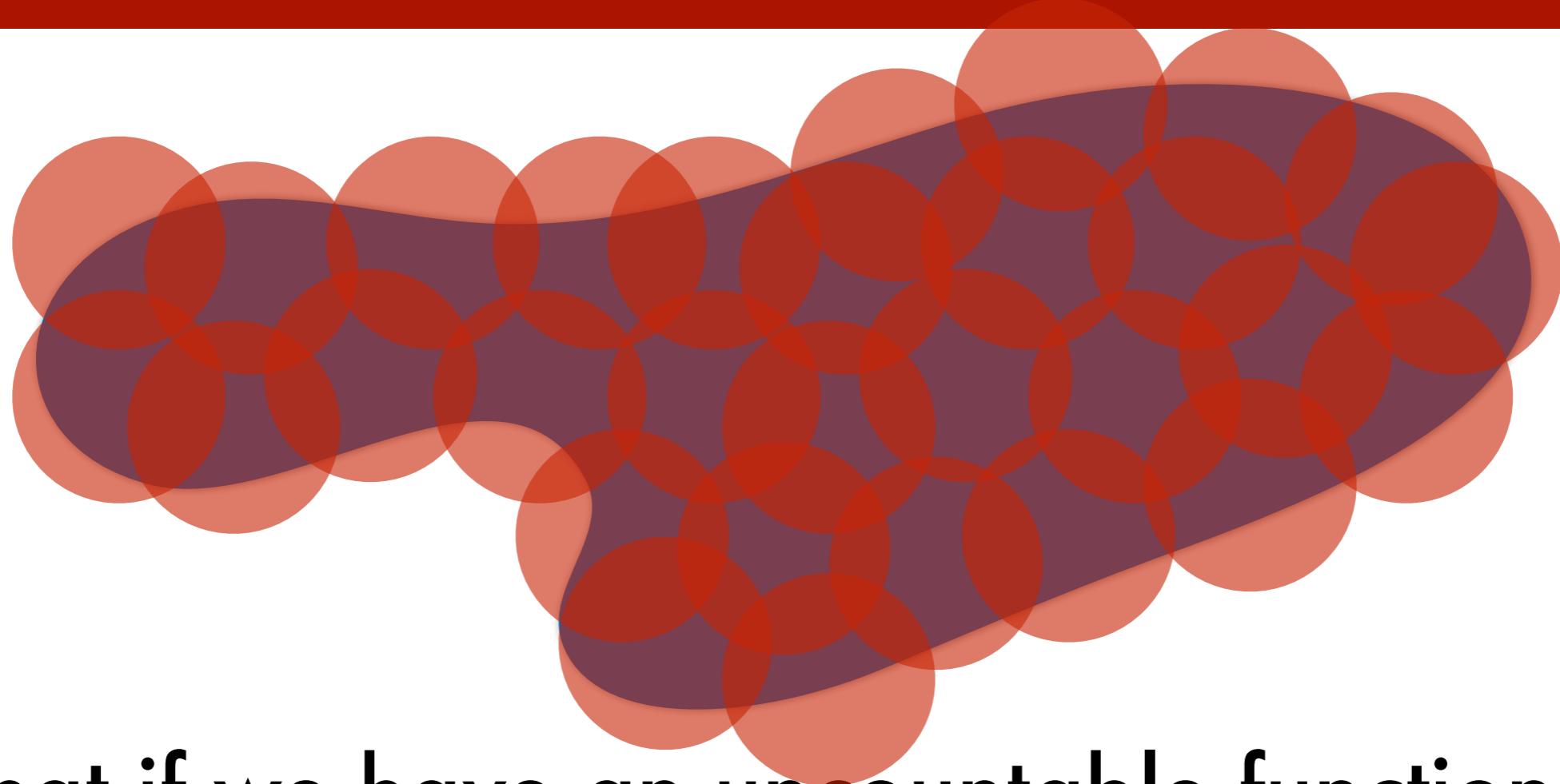
- What if we have an uncountable function class?
- Approximate by finite cover

Covering Numbers



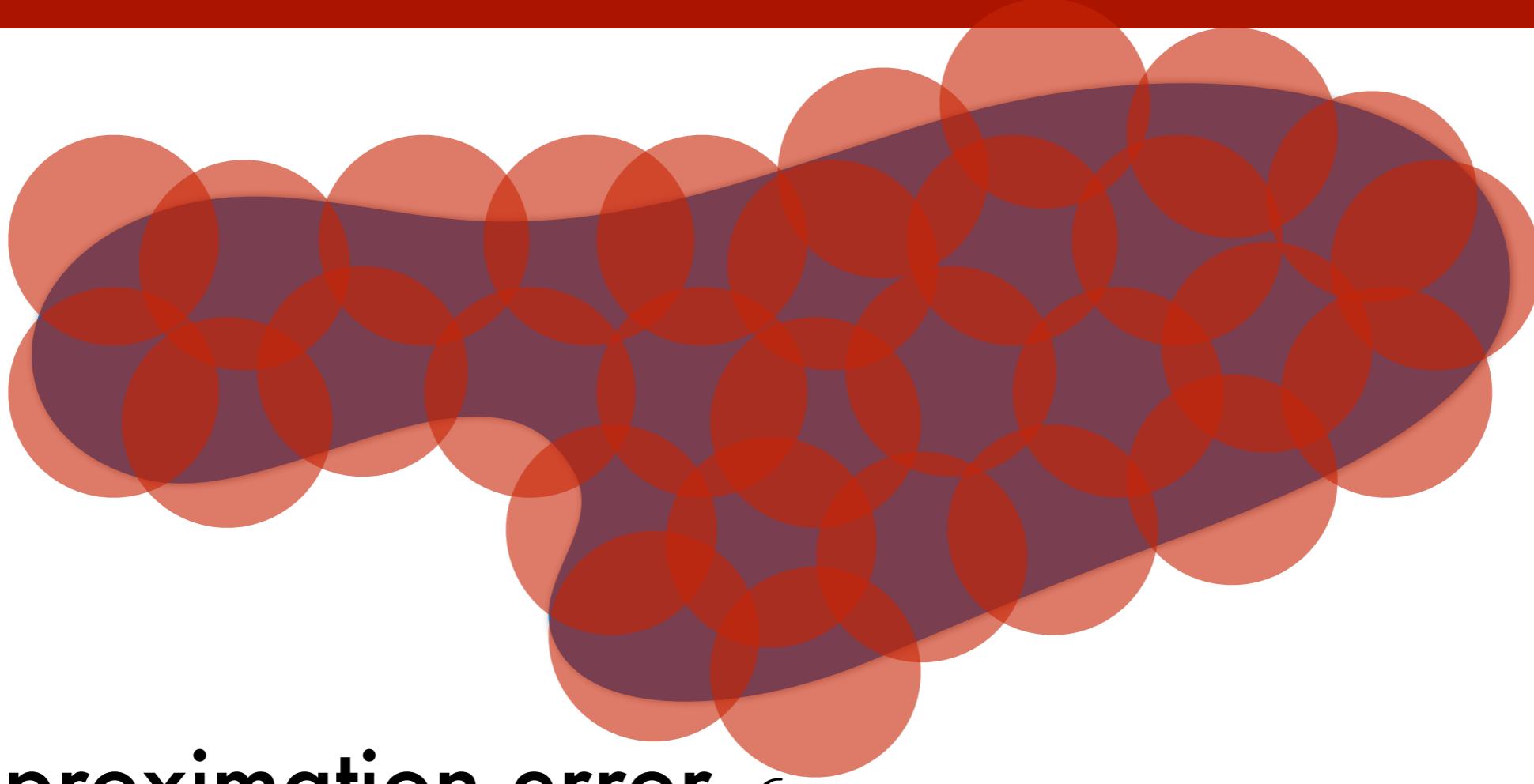
- What if we have an **uncountable** function class?
- Approximate by finite cover

Covering Numbers



- What if we have an **uncountable** function class?
- Approximate by finite cover
- Now bound depends on discretization, too

Covering Numbers

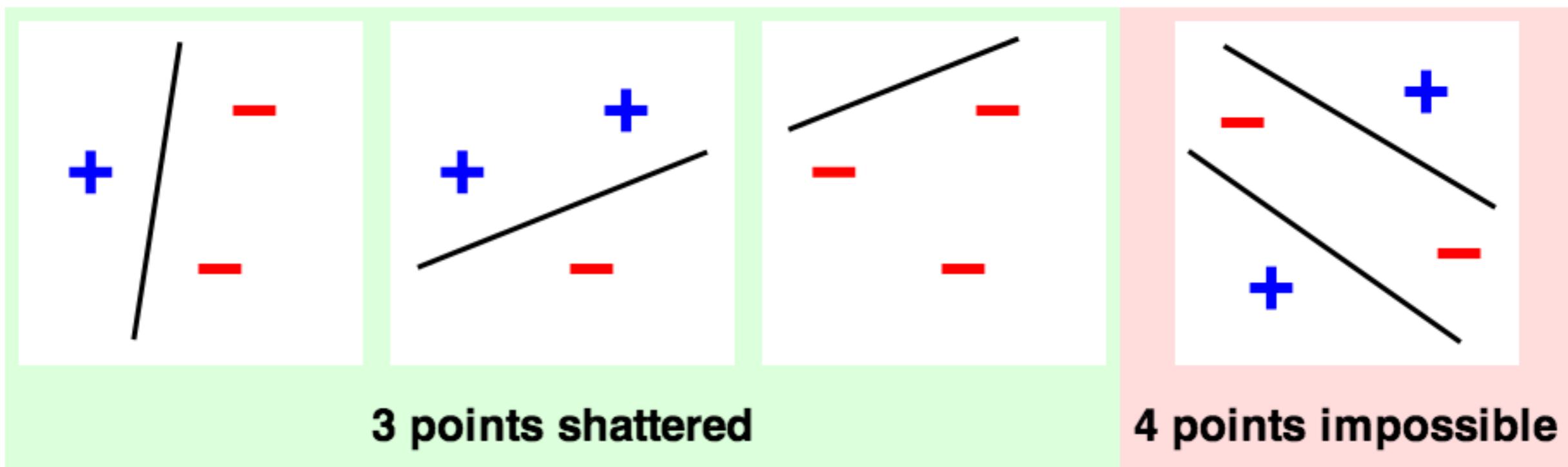


- Approximation error ϵ
- Covering number $N(\mathcal{F}, \epsilon)$ (actually need metric)

$$R[f^*] \leq \inf_{f \in \mathcal{F}} R_{\text{emp}}[f] + L \sqrt{\frac{\log N(\mathcal{F}, \epsilon) + \log 2/\delta}{2m}} + L' \epsilon$$

VC Dimension

- Binary classification problem
- Given locations, enumerate all possible ways these points can be separated
- Example - linear separation



VC Dimension

- Binary classification problem
- Given locations, enumerate all possible ways these points can be separated
- Exponential growth to VCD, then polynomial

$$R[f^*] \leq \inf_{f \in \mathcal{F}} R_{\text{emp}}[f] + \sqrt{\frac{h(\log(2m/h) + 1) + \log 4/\delta}{m}}$$

- Examples
 - d-dimensional linear functions have $h=d$
 - $\sin(x/w)$ has infinite h

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- Examples
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Rademacher Averages

- Nontrivial bound (state of the art)
- Reasonably easy to compute
- Recall McDiarmid's inequality

$$\Pr(|f(x_1, \dots, x_m) - \mathbf{E}_{X_1, \dots, X_m}[f(x_1, \dots, x_m)]| > \epsilon) \leq 2 \exp(-2\epsilon^2 C^{-2})$$

$$|f(x_1, \dots, x_i, \dots, x_m) - f(x_1, \dots, x'_i, \dots, x_m)| \leq c_i$$

$$C^2 = \sum_{i=1}^m c_i^2$$

- Bound worst case deviation

$$\Pr \left\{ \sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m l(x_i, y_i, f(x_i)) - \mathbf{E}_{(x,y)} [l(x, y, f(x))] \right| > \epsilon \right\}$$

Rademacher Averages

- **Worst case deviation**

$$\Xi(X, Y) := \sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m l(x_i, y_i, f(x_i)) - \mathbf{E}_{(x,y)} [l(x, y, f(x))] \right|$$

- **If we change single observation pair**

$$|\Xi(X, Y) - \Xi(X^{-i} \cup \{x'_i\}, Y^{-i} \cup \{y'_i\})| \leq L/m$$

Rademacher Averages

- **Worst case deviation**

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- **If we change single observation pair**

$$|\Xi(X, Y) - \Xi(X^{-i} \cup \{x'_i\}, Y^{-i} \cup \{y'_i\})| \leq L/m$$

- **Apply McDiarmid's bound to get**

$$\Pr \{ |\Xi(X, Y) - \mathbf{E}_{X,Y} [\Xi(X, Y)]| > \epsilon \} \leq 2 \exp(-2m\epsilon^2 L^{-2})$$

- **Worst case deviation not far from typical case**

Rademacher Averages

$$\begin{aligned} & \mathbf{E}_{X,Y} \left[\sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m l(x_i, y_i, f(x_i)) - \mathbf{E}_{(x,y)} [l(x, y, f(x))] \right| \right] \\ = & \mathbf{E}_{X,Y} \left[\sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m l(x_i, y_i, f(x_i)) - \mathbf{E}_{X',Y'} \frac{1}{m} \sum_{i=1}^m [l(x'_i, y'_i, f(x'_i))] \right| \right] \\ \leq & \mathbf{E}_{X,Y,X',Y'} \left[\sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m [l(x_i, y_i, f(x_i)) - l(x'_i, y'_i, f(x'_i))] \right| \right] \\ = & \mathbf{E}_{X,Y,X',Y'} \mathbf{E}_\sigma \left[\sup_{f \in \mathcal{F}} \left| \frac{1}{m} \sum_{i=1}^m \sigma_i [l(x_i, y_i, f(x_i)) - l(x'_i, y'_i, f(x'_i))] \right| \right] \\ \leq & \frac{2}{m} \mathbf{E}_{X,Y} \mathbf{E}_\sigma \left[\sup_{f \in \mathcal{F}} \sum_{i=1}^m \sigma_i l(x_i, y_i, f(x_i)) \right] \end{aligned}$$

Rademacher Averages

- Putting it all together

$$R[f] \leq R_{\text{emp}}[f] + 2\mathcal{R}[\mathcal{F}, m] + L\sqrt{\frac{\log 2/\delta}{2m}}$$

behavior for
random labels

averaging

- Rademacher average can be bounded easily for linear function classes by solving a convex optimization problem.

Some Alternatives

- Validation set
 - Train on training set (e.g. 90% of the data)
 - Check performance on remaining 10%
 - Use only if dataset is huge and few tests
- Crossvalidation
 - Average over validation sets (e.g. 10 fold)
 - Nested cross-validation for model selection
(e.g. 10-fold in each fold to find parameters)
- Bayesian statistics