Quadratic Programming 10701 Recitations 3

#### Mu Li

Computer Science Department Cargenie Mellon University

February 5, 2013

◆□▶ ◆□▶ ◆三▶ ◆三▶ ○○ のへで

### What is Quadratic Programming

The quadratic programming is formulated as

$$\min_{w} \left\{ \frac{1}{2} w^{T} Q w + c^{T} w \right\} \text{ subject to } \begin{cases} A w \leq b \\ E w = d \end{cases}$$

where  $Q \in \mathbb{R}^{n \times n}$  and is symmetric,  $w, c \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ ,  $E \in \mathbb{R}^{p \times n}$ , and  $d \in \mathbb{R}^p$ ,

- constraint optimization: minimize objective + constraints
- w is feasible if satisfying the constraints
- ▶ local minimizer: for any feasible *u* around *w*,  $f(w) \le f(u)$

▶ global minimizer: for any feasible u,  $f(w) \le f(u)$ 

### What is Quadratic Programming

The quadratic programming is formulated as

$$\min_{w} \left\{ \frac{1}{2} w^{T} Q w + c^{T} w \right\} \text{ subject to } \begin{cases} A w \leq b \\ E w = d \end{cases}$$

where  $Q \in \mathbb{R}^{n \times n}$  and is symmetric,  $w, c \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ ,  $E \in \mathbb{R}^{p \times n}$ , and  $d \in \mathbb{R}^p$ ,



▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

# Convex QP

If Q is positive semidefinite (definite), that is x<sup>T</sup>Qx ≥ 0 (> 0) for any x, the objective function is (strongly) convex. If feasible w exists, any local minimizer is global, and there is at least one (a unique) global minimizer



- If Q = 0, QP reduces to linear programming
- Solving general QP is NP-hard, but several algorithms solve convex QP in polynomial time

## An Example

Consider the following example:

$$\min_{x,y} \{x^2 + 4(y - 4)^2\} \text{ subject to } \begin{cases} x + y \le 7, -x + 2y \le 4\\ x \ge 0, y \ge 0, y \le 4 \end{cases}$$
  
We have  
$$Q = \begin{bmatrix} 2 & 0\\ 0 & 8 \end{bmatrix} c = \begin{bmatrix} 0\\ -32 \end{bmatrix} A = \begin{bmatrix} 1 & 1\\ -1 & 2\\ -1 & 0\\ 0 & -1\\ 0 & 1 \end{bmatrix} b = \begin{bmatrix} 7\\ 4\\ 0\\ 0\\ 4 \end{bmatrix} E = d = 0$$

run Matlab command x = quadprog(Q,c,A,b) and get the results

x =

2.0000 3.0000



### QP and SVM

Recall the Support Vector Machine:

$$\min_{w} \frac{1}{2} \|w\|^2 \text{ subject to } y_i[\langle x_i, w \rangle + b_0] \ge 1 \text{ for any } i,$$

where  $w \in \mathbb{R}^{p}, x_{i} \in \mathbb{R}^{p}$ , and  $y_{i} \in \{-1, 1\}$ 

It is straightforward to formulate it as QP

$$Q = I, A = \begin{bmatrix} -y_1 x_1 \\ \vdots \\ -y_n x_n \end{bmatrix}, b = \begin{bmatrix} y_1 b_0 - 1 \\ \vdots \\ y_n b_0 - 1 \end{bmatrix}, c = E = d = 0$$

Solving SVM: x = quadprog(Q,c,A,b), suitable for medium size n

# Questions?