

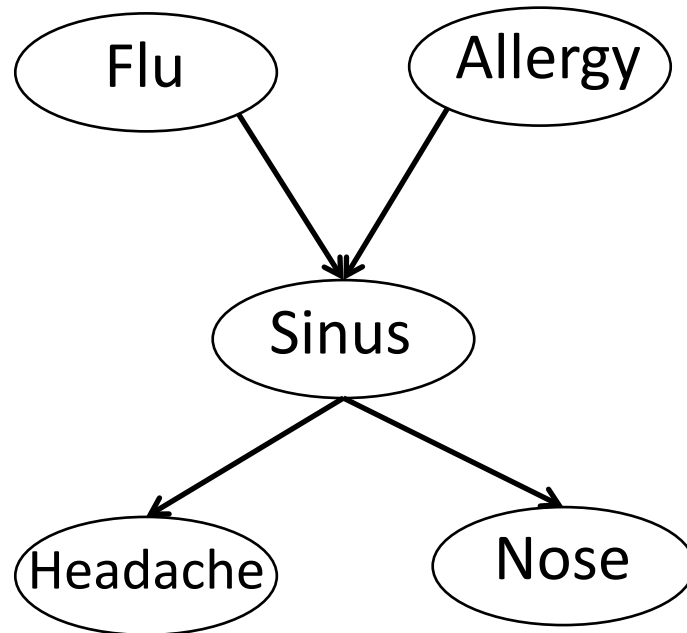
Bayes Nets

10-701 recitation

04-02-2013

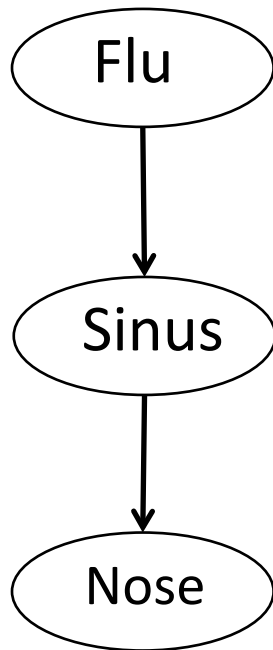
Bayes Nets

- Represent dependencies between variables
- Compact representation of probability distribution
- Encodes causal relationships



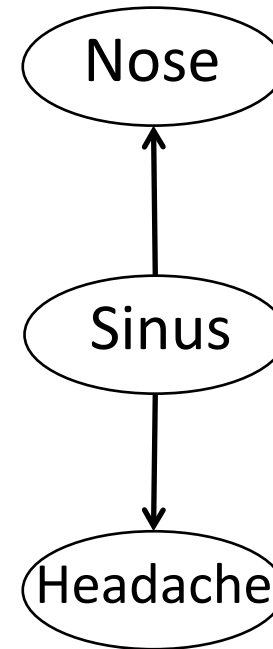
Conditional independence

- $P(X,Y|Z) = P(X|Z) \times P(Y|Z)$



$F \text{ not } \perp N$

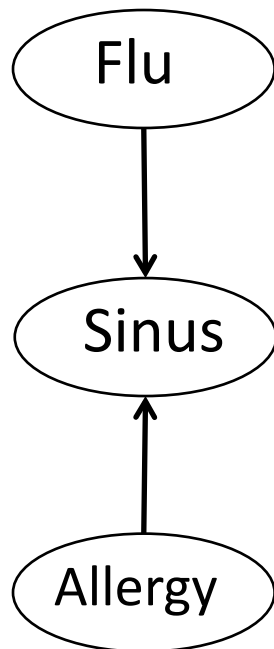
$F \perp N \mid S$



$N \text{ not } \perp H$

$N \perp H \mid S$

Conditional independence



$F \perp A$

$F \text{ not } \perp A \mid S$

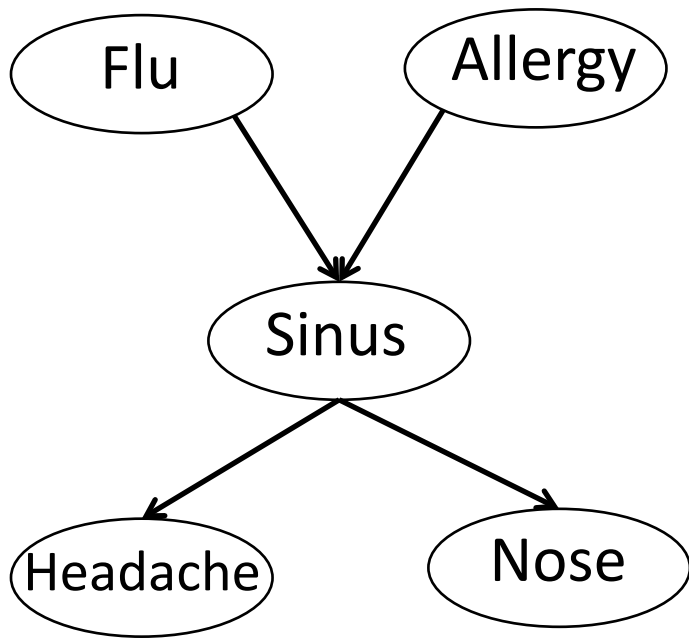
- Explaining away:
 - $P(F = t \mid S = t)$ is high
 - But $P(F = t \mid S = t, A = t)$ is lower

Joint probability distribution

- Chain rule of probability:

$$P(X_1, X_2, \dots, X_n) = P(X_1) P(X_2 | X_1) \dots P(X_n | X_1, X_2, \dots, X_{n-1})$$

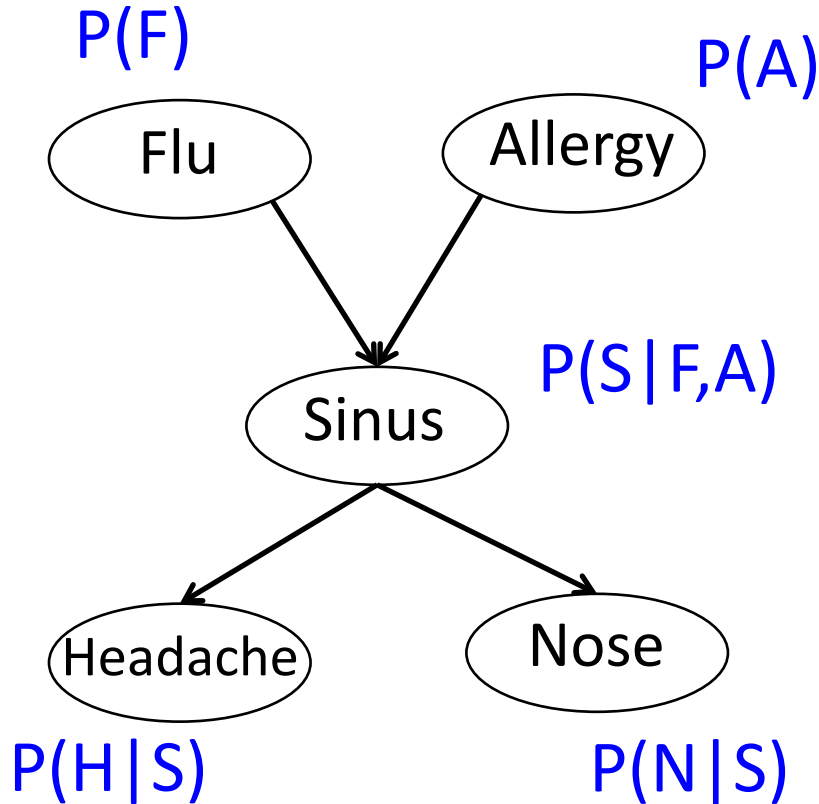
Joint probability distribution



- Chain rule of probability:
$$P(F,A,S,H,N) = P(F) P(A|F)$$
$$P(S|A,F) P(H|F,A,S)$$
$$P(N|F,A,S,H)$$

↑
Table with 2^5 entries!

Joint probability distribution



- Local markov assumption:
A variable X is independent of its non-descendants given its parents

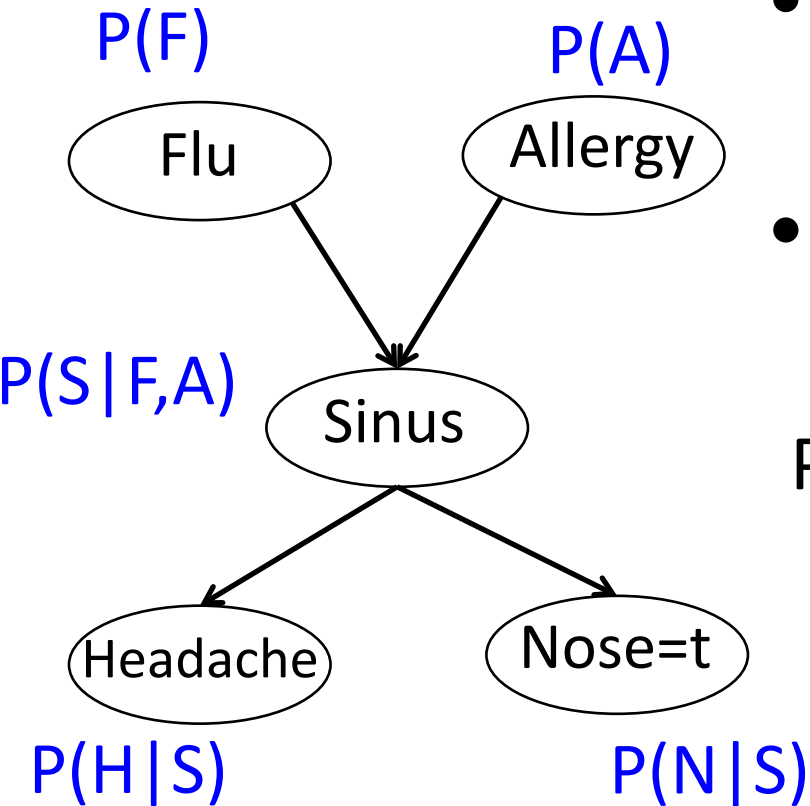
$$P(F,A,S,H,N) = P(F) P(A)$$

$$P(S|A,F) P(H|S)$$

$$P(N|S)$$

	F = t, A = t	F = t, A = f	F = f, A = t	F = f, A = f
S = t	0.9	0.8	0.7	0.1
S = f	0.1	0.2	0.3	0.9

Queries, Inference

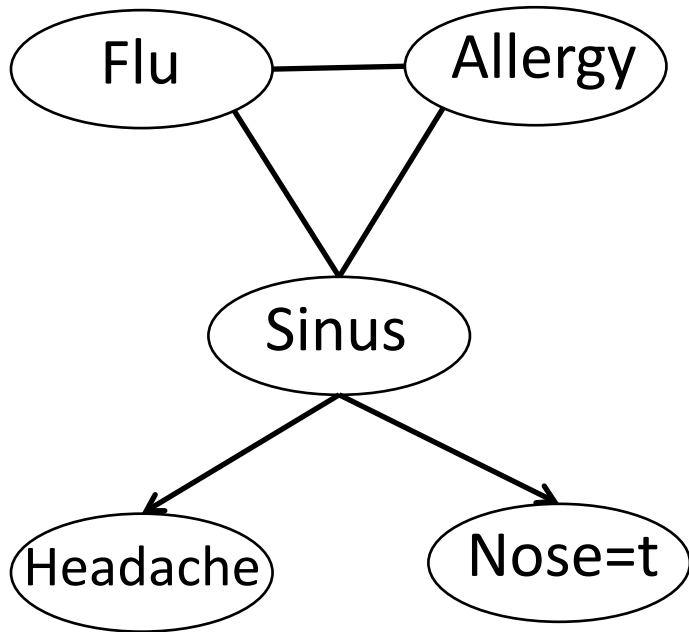


- $P(F = t \mid N = t) ?$

- $P(F=t \mid N=t) = P(F=t, N=t) / P(N=t)$

$$\begin{aligned} P(F, N=t) &= \sum_{A, S, H} P(F, A, S, H, N=t) \\ &= \sum_{A, S, H} P(F) P(A) \\ &\quad P(S|A, F) P(H|S) \\ &\quad P(N=t|S) \end{aligned}$$

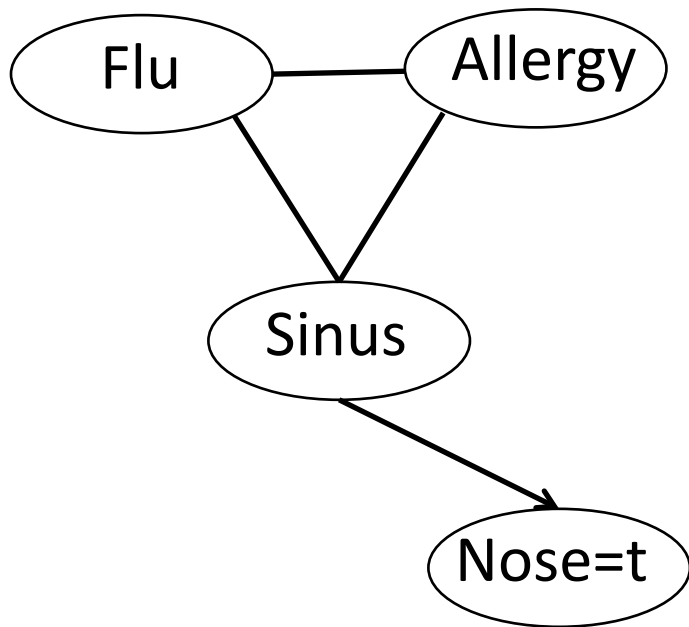
Moralizing the graph



- Eliminating A will create a factor with F and S
- To assess complexity we can moralize the graph: connect parents

Chose an optimal order

If we start with H:

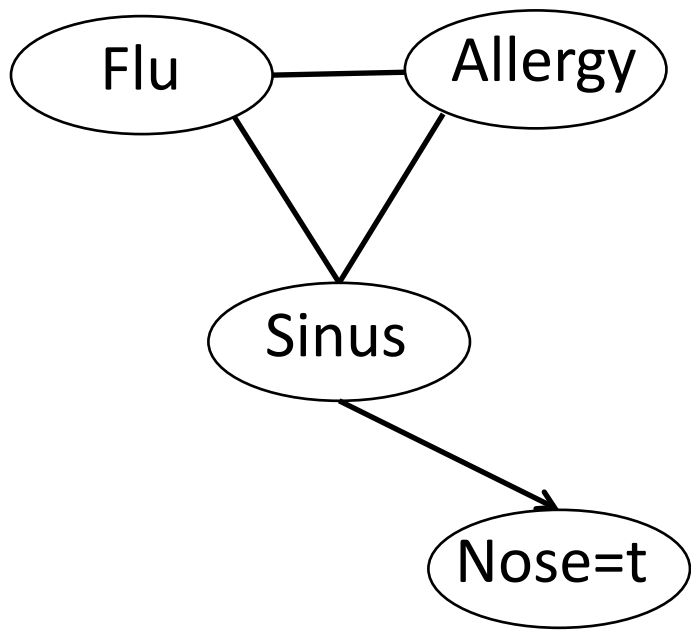


$$P(F, N=t) = \sum_{A, S} P(F) P(A)$$

$$P(S | A, F) P(N=t | S)$$

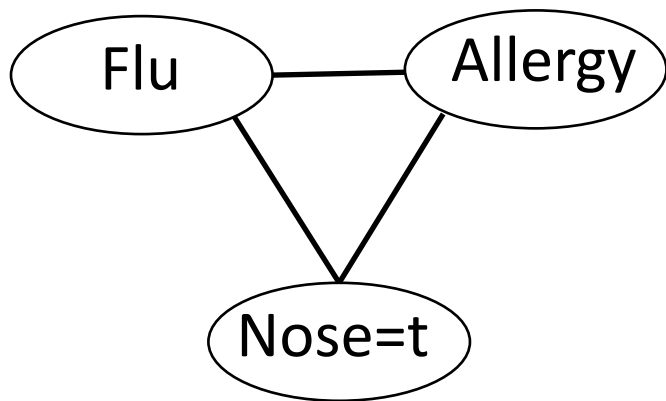
$$\sum_H P(H | S) \leftarrow =1$$

$$= \sum_{A, S} P(F) P(A) P(S | A, F) P(N=t | S)$$



Removing S

$$\begin{aligned}
 P(F, N=t) &= \sum_{A, S} P(F) P(A) P(S | A, F) \\
 &\quad P(N=t | S) \\
 &= \sum_A P(F) P(A) \\
 &\quad \sum_S P(S | A, F) P(N=t | S) \\
 &= \sum_A P(F) P(A) g_1(F, A)
 \end{aligned}$$



Removing A

$$\begin{aligned}
 P(F, N=t) &= P(F) \sum_A P(A) g_1(F, A) \\
 &= P(F) g_2(F)
 \end{aligned}$$

\swarrow $=P(N=t|F)$

$$P(F=t | N=t) = P(F=t, N=t) / P(N=t)$$

$$P(N=t) = \sum_F P(F, N=t)$$

Independencies and active trails

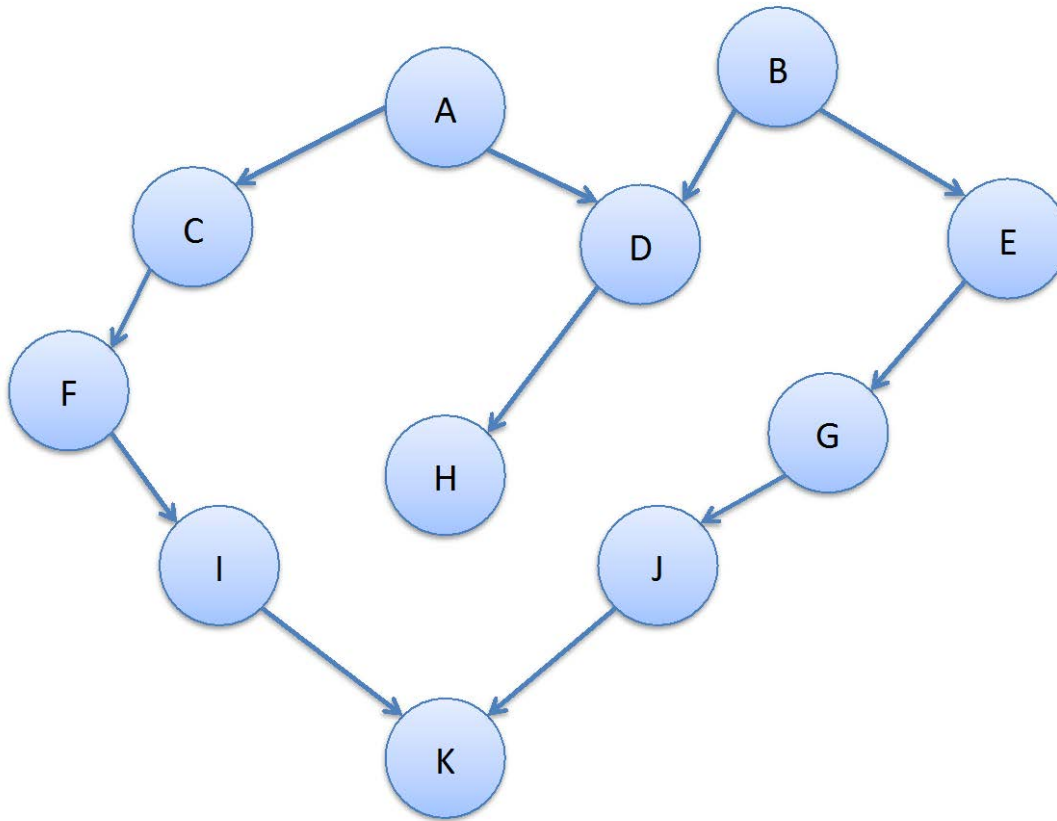
Is $A \perp H$? When is it not?

A is not $\perp H$ when given C and F or F' or F'' and not {B,D,E,G}

Independencies and active trails

- Active trail between variables $X_1, X_2 \dots X_{n-1}$ when:
 - $X_{i-1} \rightarrow X_i \rightarrow X_{i+1}$ and X_i not observed
 - $X_{i-1} \leftarrow X_i \leftarrow X_{i+1}$ and X_i not observed
 - $X_{i-1} \leftarrow X_i \rightarrow X_{i+1}$ and X_i not observed
 - $X_{i-1} \rightarrow X_i \leftarrow X_{i+1}$ and X_i or one of its descendants is observed

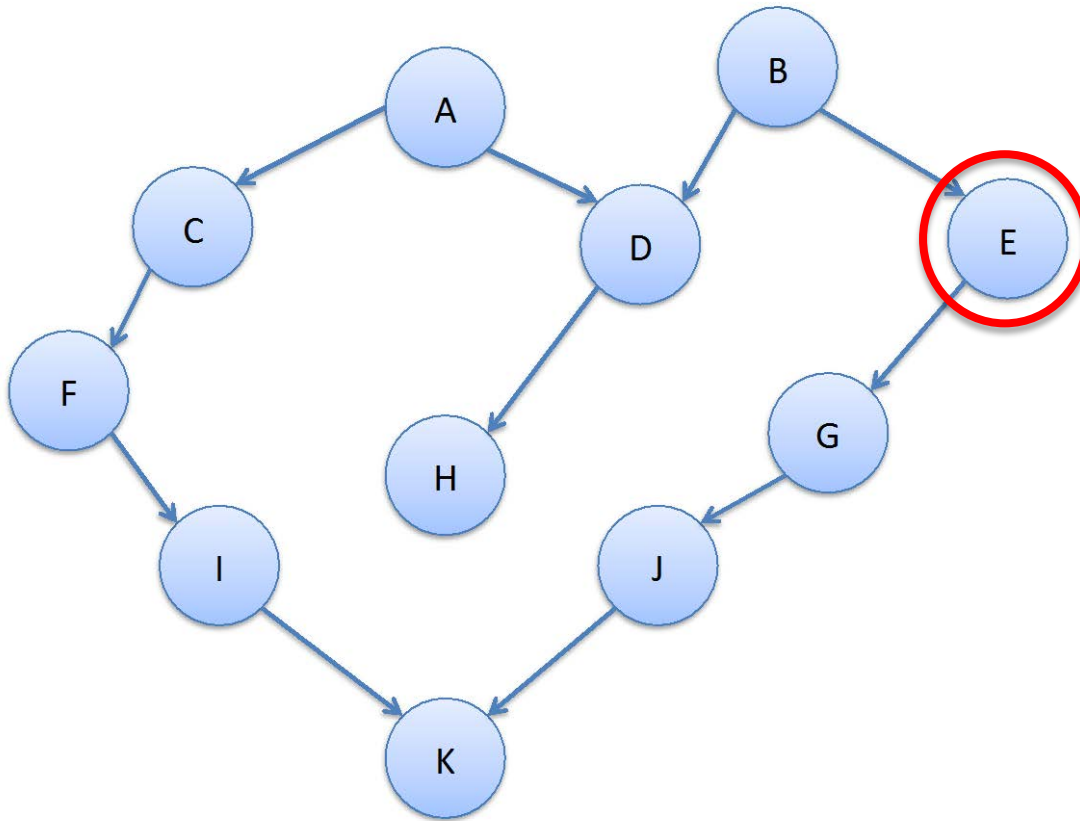
Independencies and active trails



$A \perp B ?$

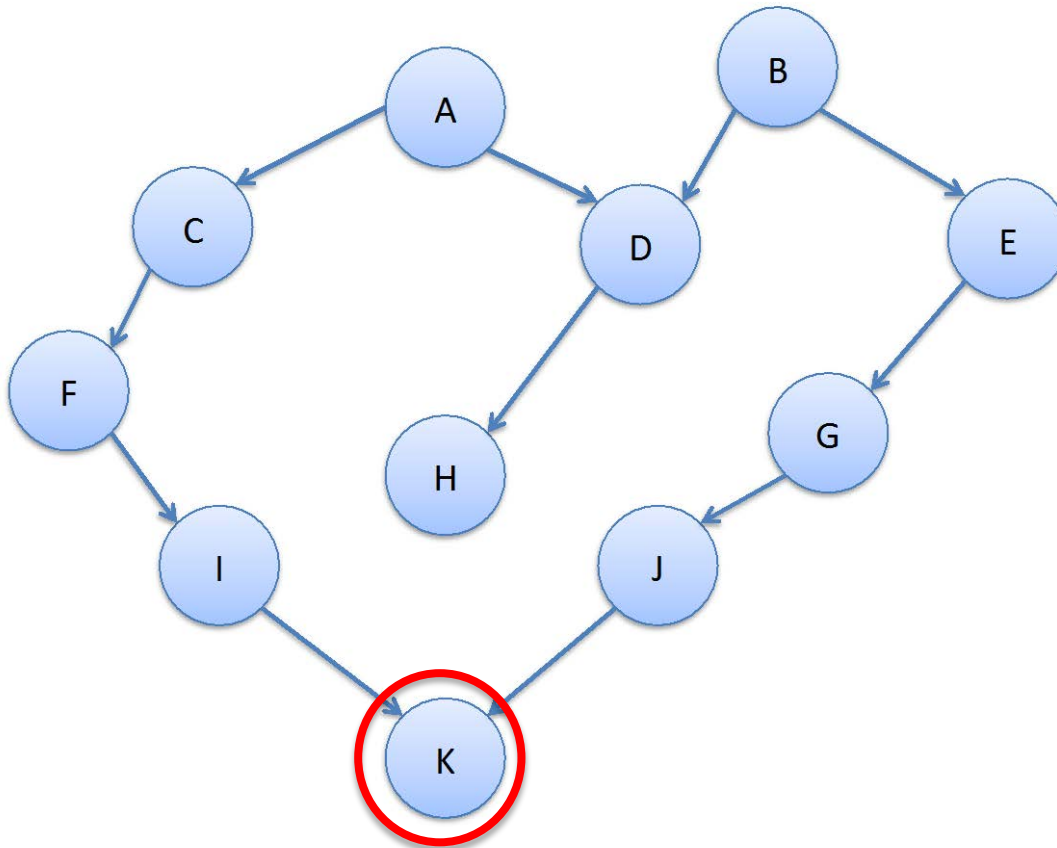
Independencies and active trails

$B \perp\!\!\!\perp G \mid E ?$



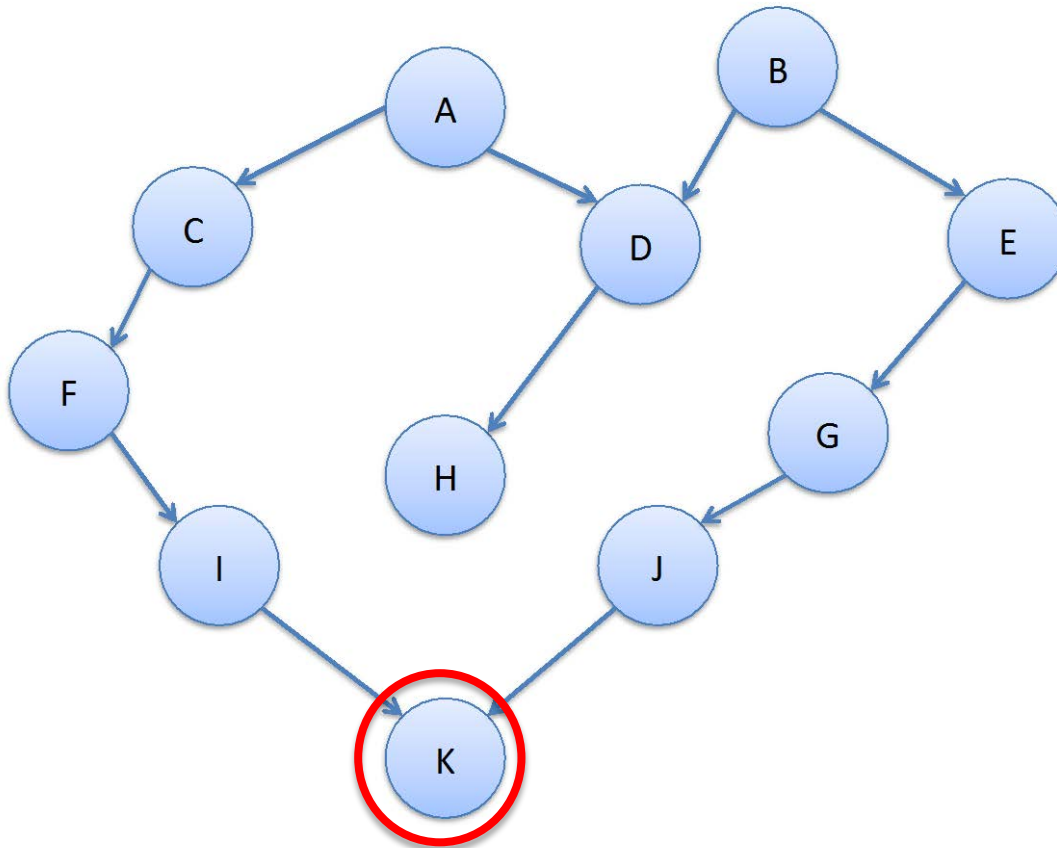
Independencies and active trails

$I \perp\!\!\!\perp J \mid K ?$



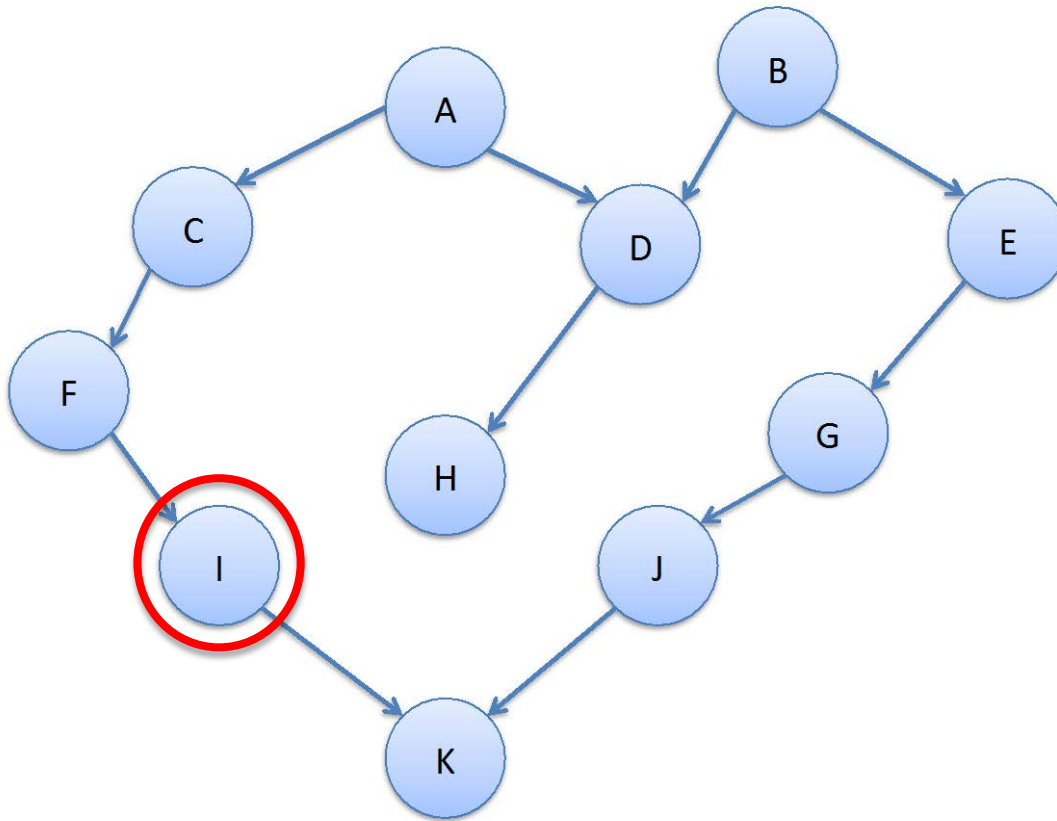
Independencies and active trails

$E \perp\!\!\!\perp F \mid K ?$



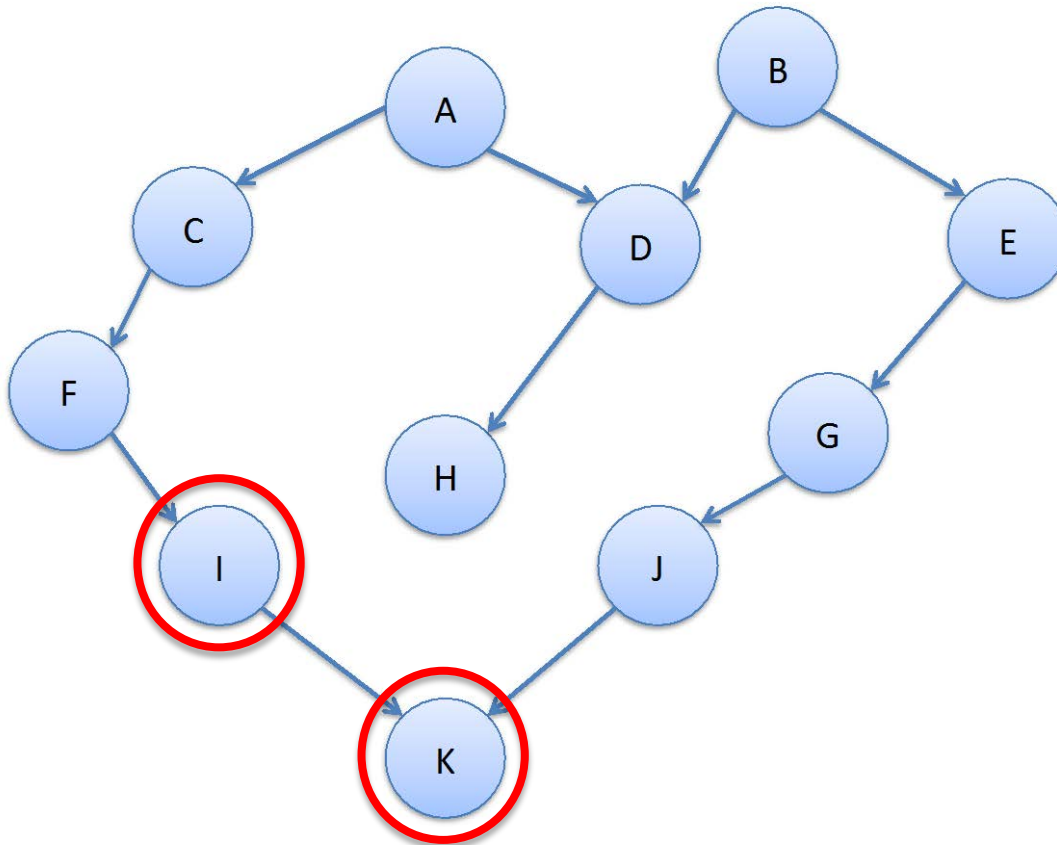
Independencies and active trails

$F \perp K \mid I ?$



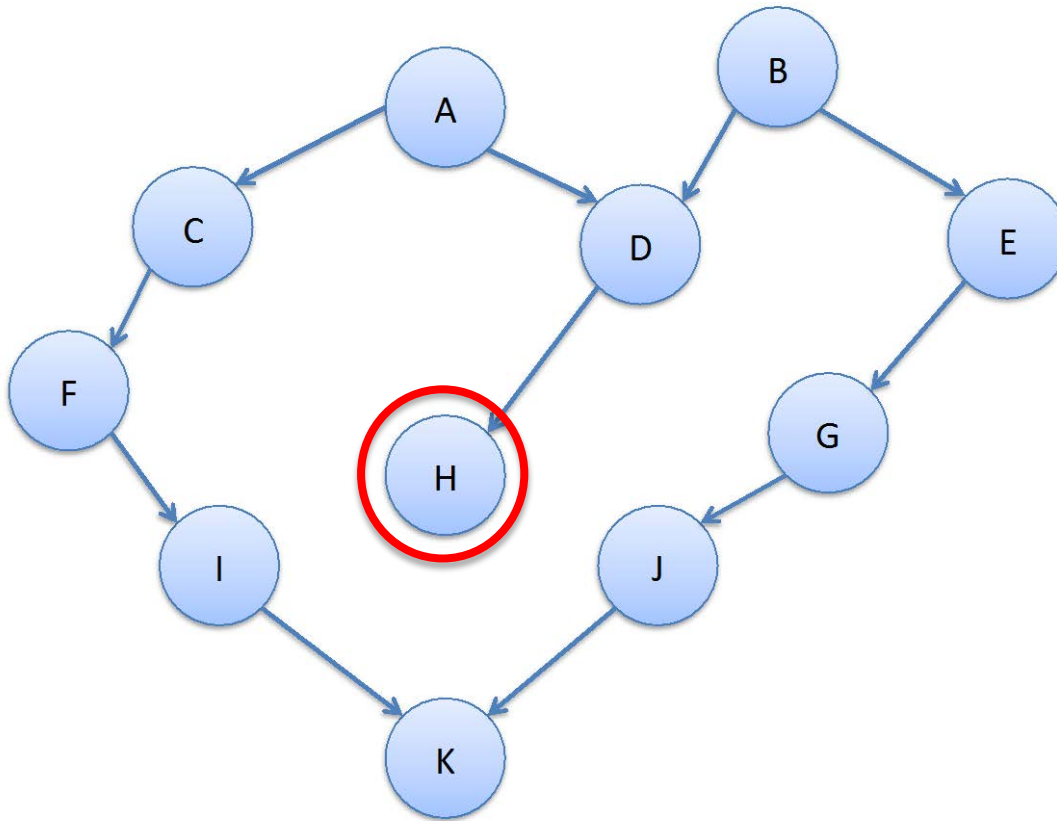
Independencies and active trails

$E \perp\!\!\!\perp F \mid I, K$?



Independencies and active trails

$F \perp G \mid H ?$



Independencies and active trails

$F \perp G \mid H, A ?$

